

JASRI Acc Div. Linac Group
H. Hanaki

*Beam energy instability of SPring-8 linac is
0.01% rms.*

How have we achieved it ...

1 Overview of SPring-8 linac

2 Beam stabilization

- Stabilization of RF amplitude & phase
- Synchronization of linac RF with ring RF
- Energy compression system (ECS)
- Feedback control

3 Summary

Injection beam

	Booster synchrotron		NewSUBARU
Beam energy	1 GeV	1 GeV	1 GeV
Repetition rate	1 pps	1 pps	1 pps
Pulse width	1 ns	40 ns	1 ns
Peak current	2 A	70 mA	200 mA
Energy spread	$\pm 0.3 \%$	$\pm 0.5 \%$	$\pm 0.2 \%$



Beam energy	1.2 GeV max.
Beam current	2 A
Beam pulse width	250 ps, 1 ns, 40 ns
RF frequency	2856 MHz
Repetition	60 pps
Klystron	80 MW x 13
Acc. structure	3 m x 26
Length of linac	140 m

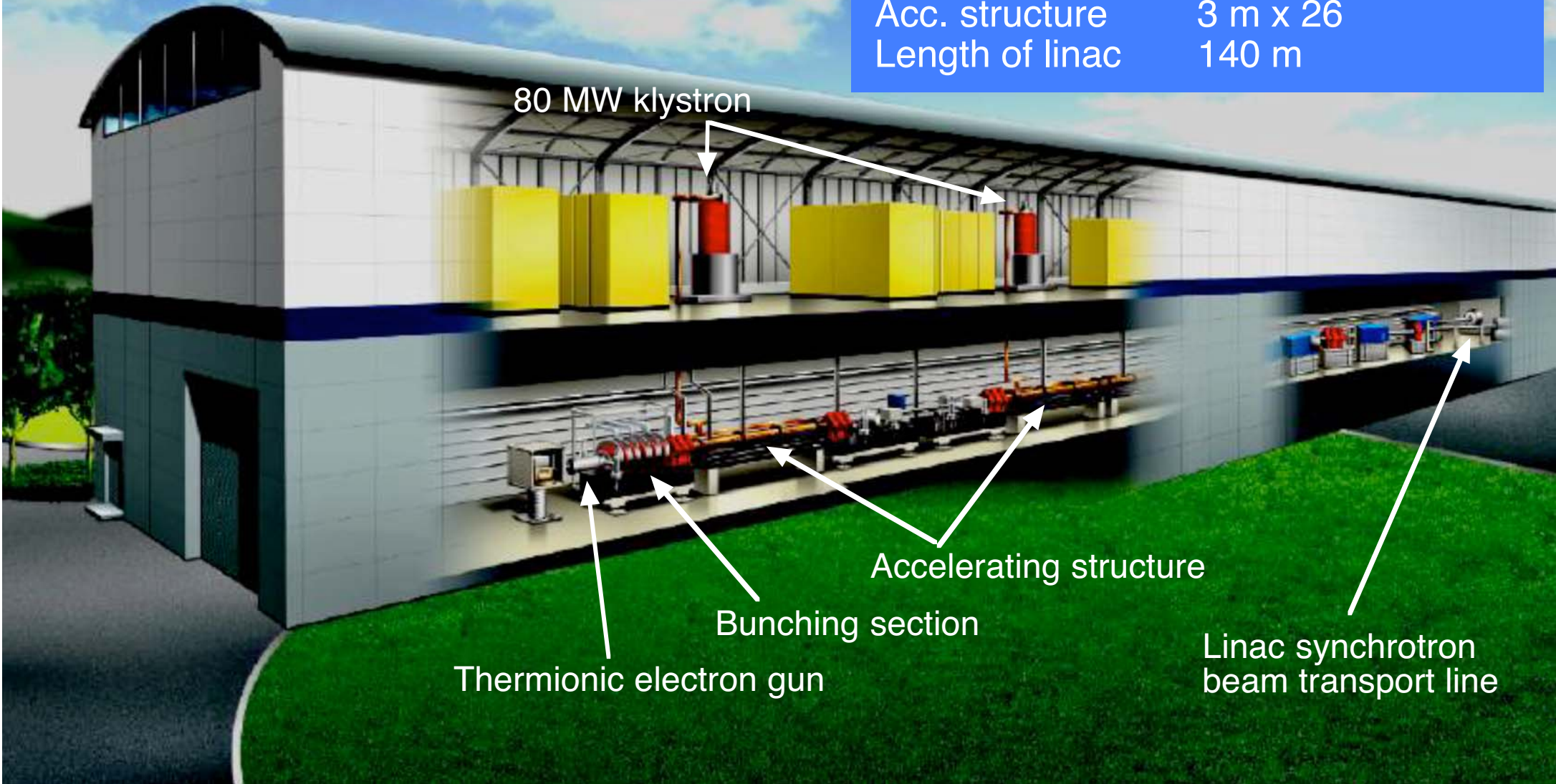
80 MW klystron

Accelerating structure

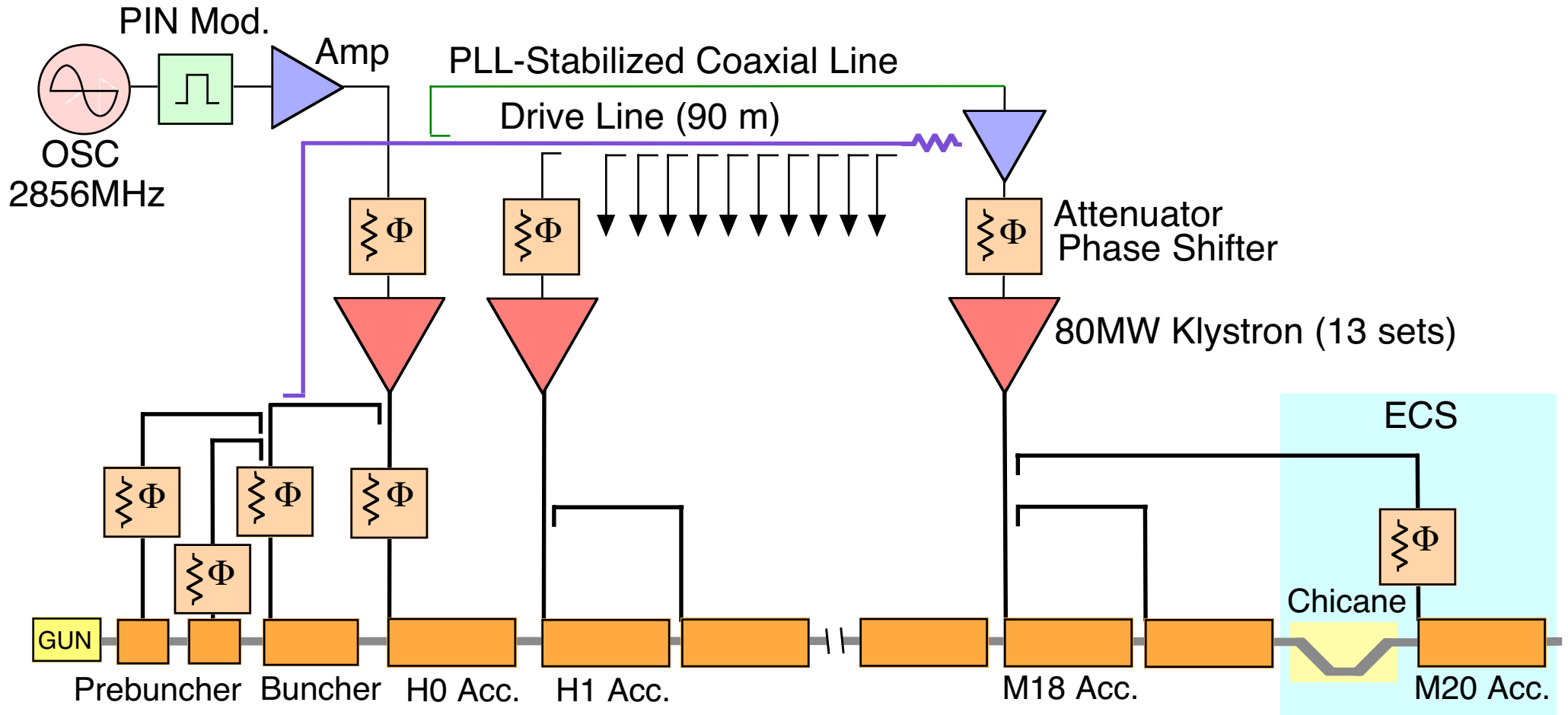
Bunching section

Thermionic electron gun

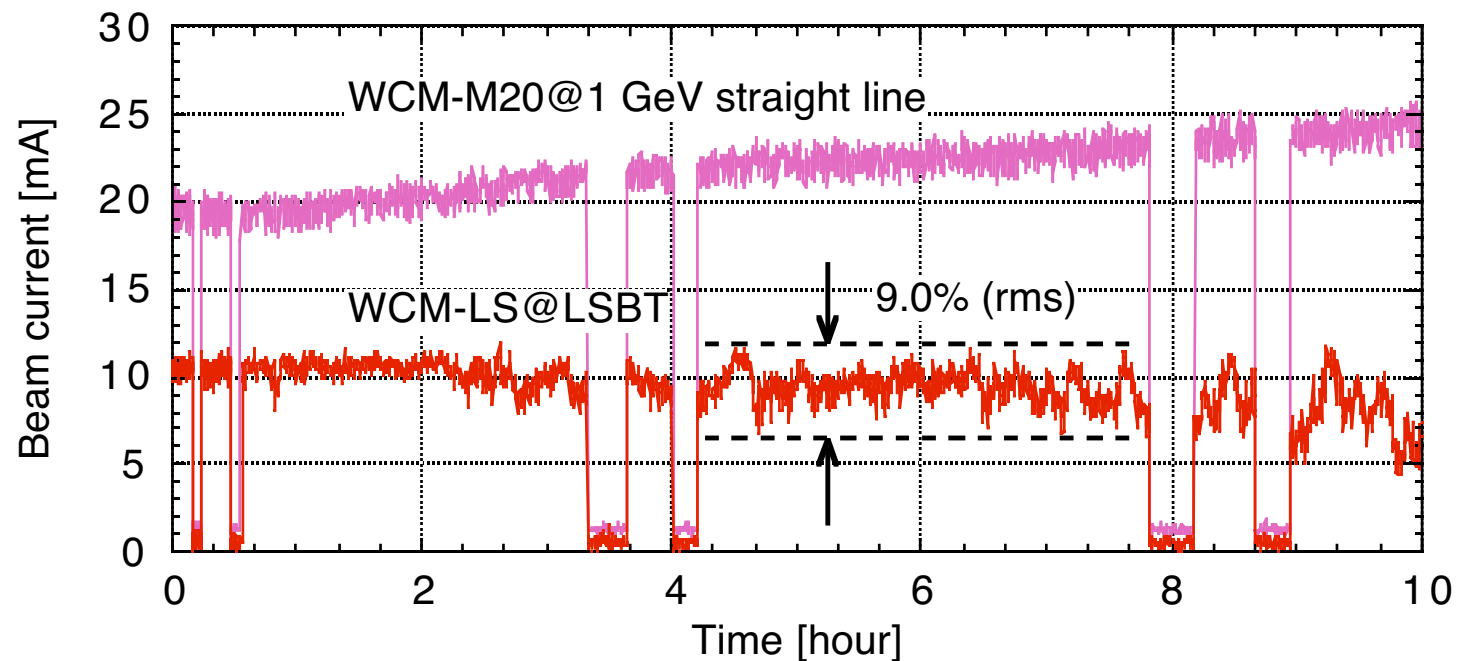
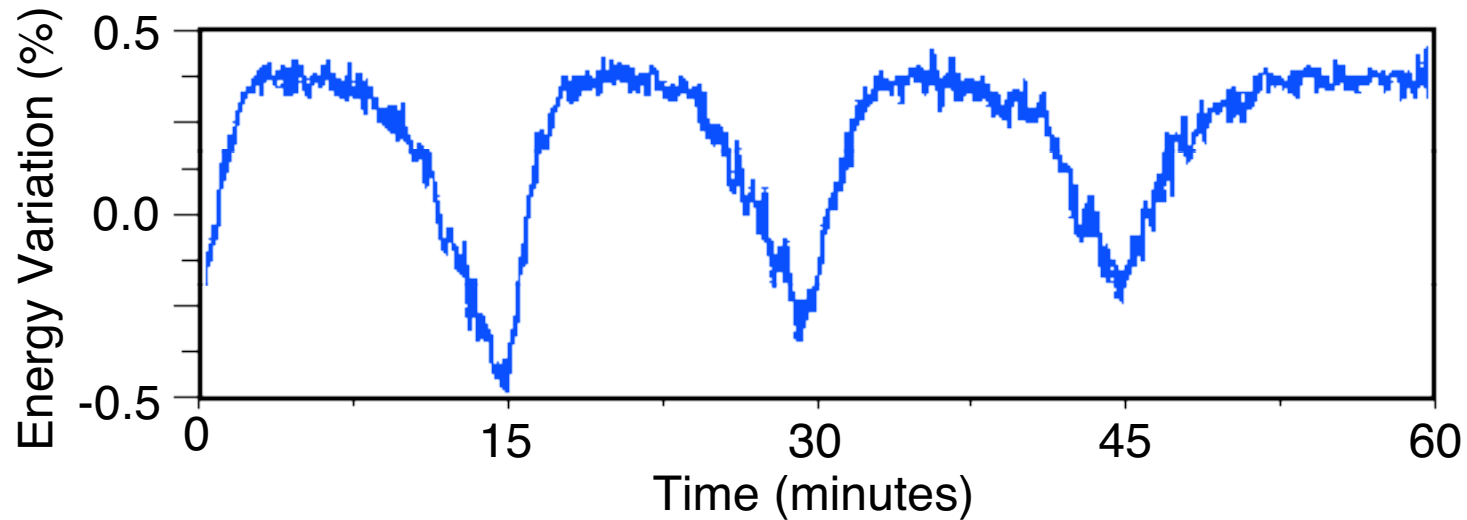
Linac synchrotron
beam transport line



Present Linac RF System



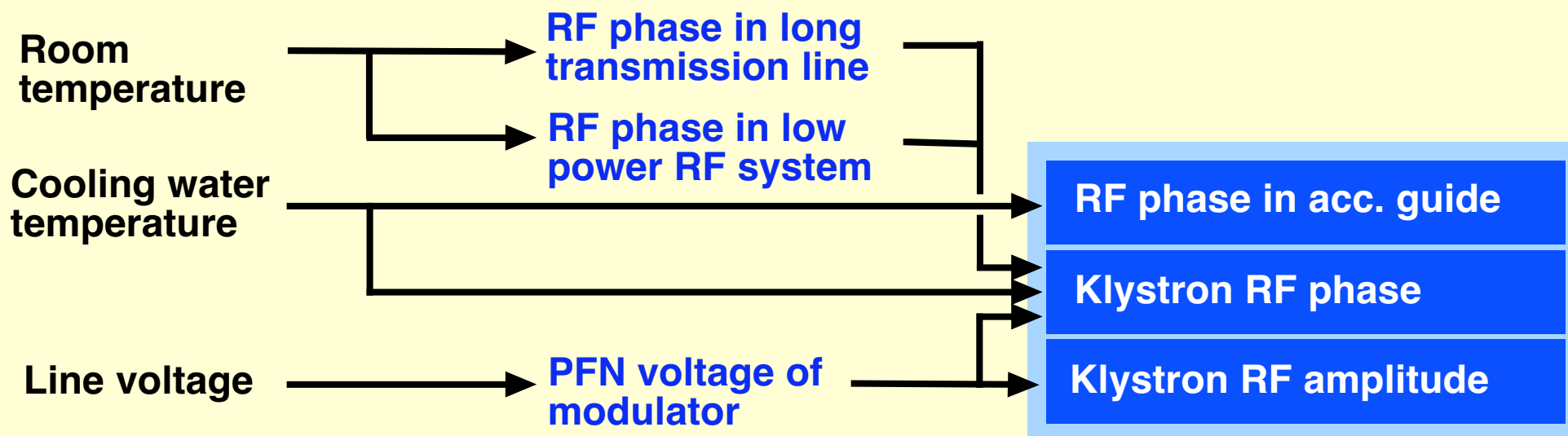
Beam Injection Instability in 1998



- 1 Stabilization of RF amplitude & phase
 - ➔ Investigate variation chains
 - Stabilization of their origins or devices
- 2 Reduce beam loading fluctuation ← **No SHB!**
 - ➔ Synchronization of linac RF with ring RF
- 3 Compensate accidental energy variation
 - ➔ Introduce Energy Compression System (ECS)
- 4 Reduce residual beam position drift
 - ➔ Introduce feedback control

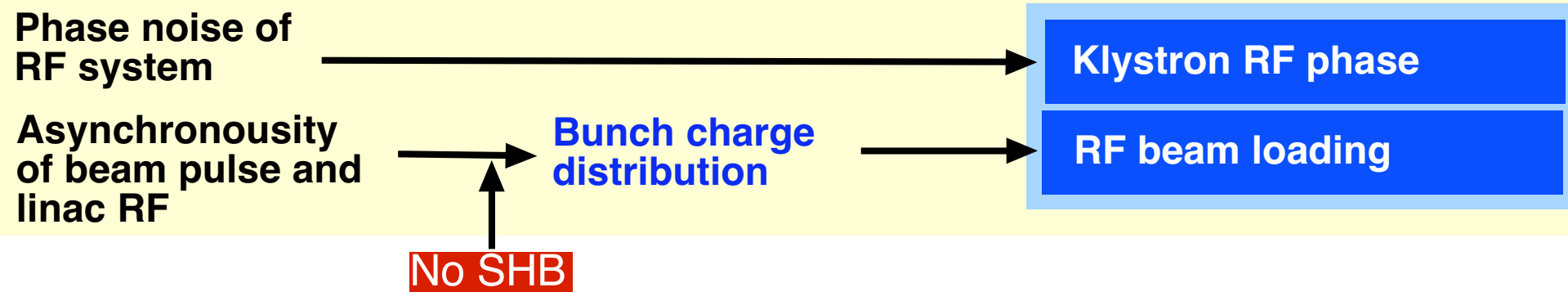
Variation chains in SPring-8 linac

Long Period Variation Chain



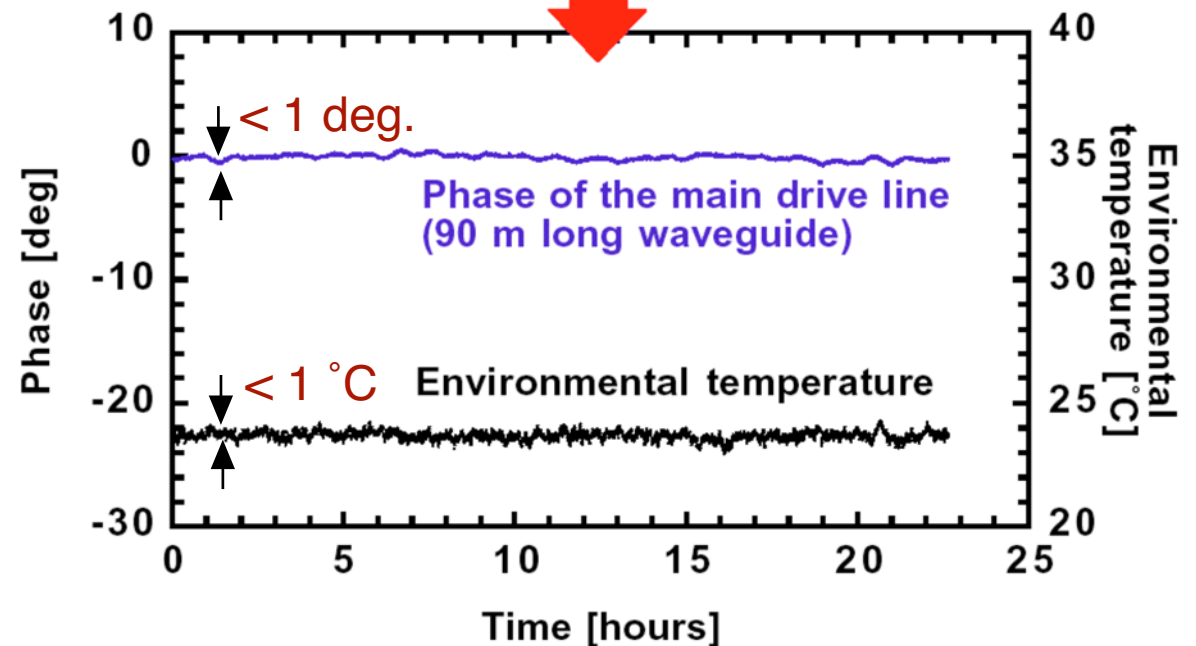
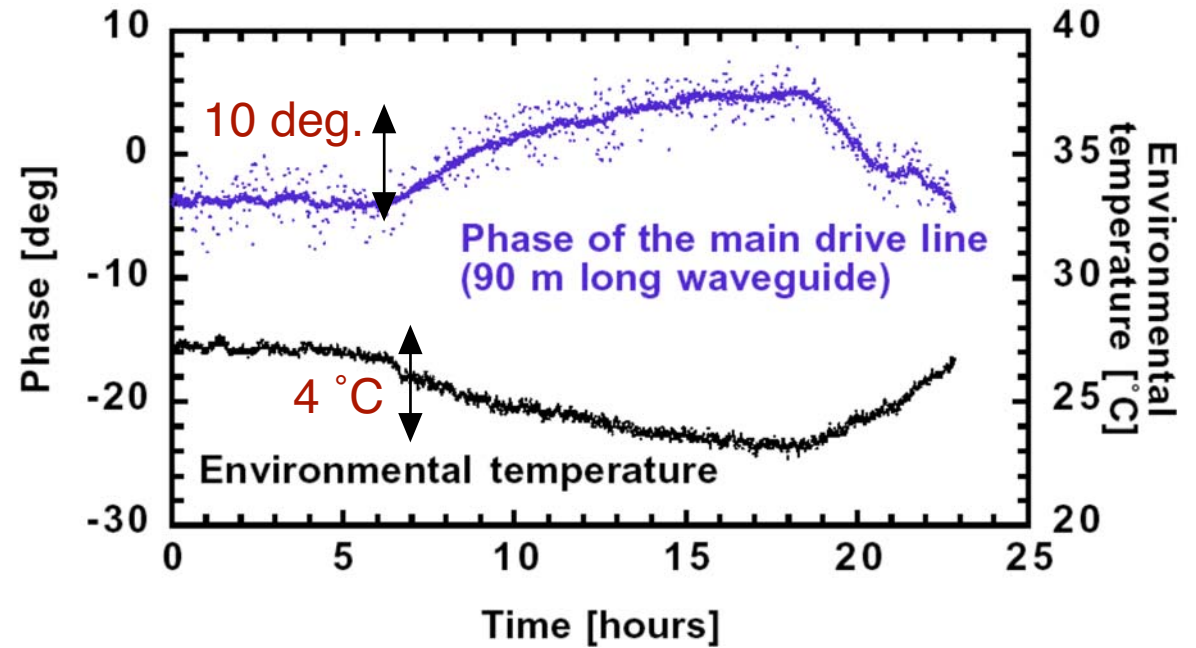
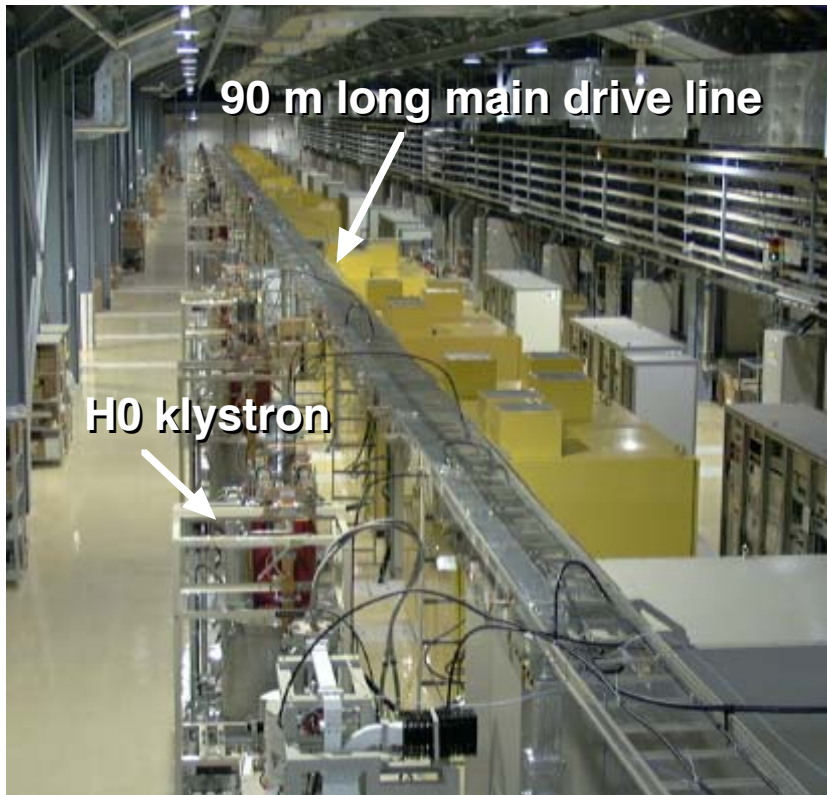
Beam energy variation

Shot-by-Shot Variation Chain



- ▶ **Room temperature stabilization**
 - Readjustment of air conditioners
 - Covering the long drive line with heat jackets
 - Circulating temperature stabilized water inside the jackets
- ▶ **Klystron temperature stabilization**
 - Improvement of water cooling system
- ▶ **Isolate line voltage variation**
 - Stabilization of Pulse Forming Network (PFN) voltage by improving modulator regulation circuits

Room temperature stabilization



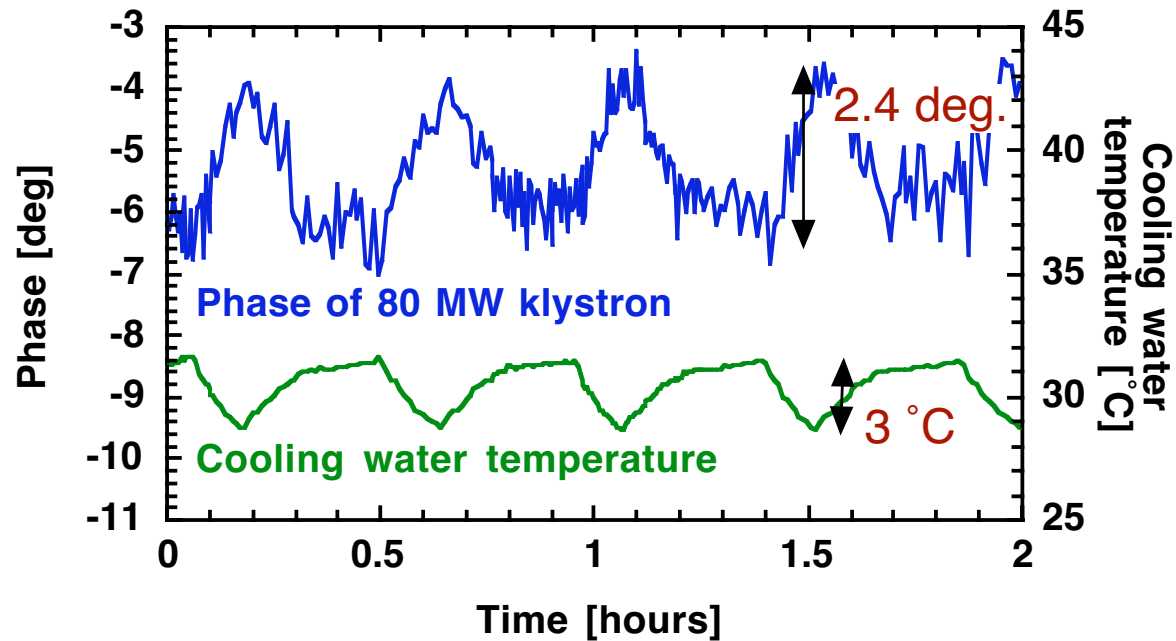
Phase variation

10 deg. / 4 °C



< 1 deg. / 1 °C

Klystron temperature stabilization



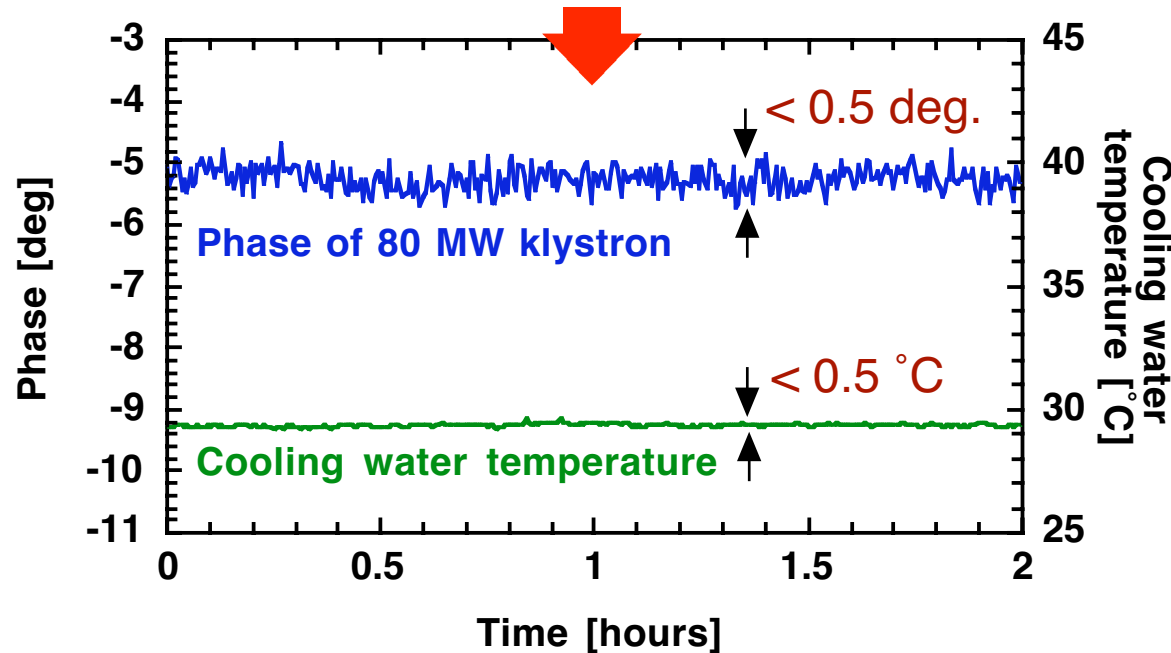
Phase variation

2.4 deg. / 3 °C

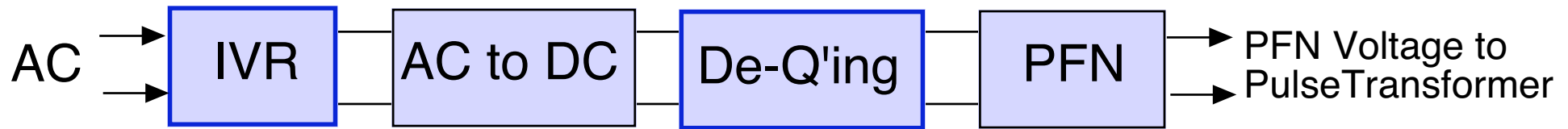


< 0.5 deg. / 0.5 °C

Calculated temperature coefficient: 0.74 deg. / °C



Improvement of modulator regulation



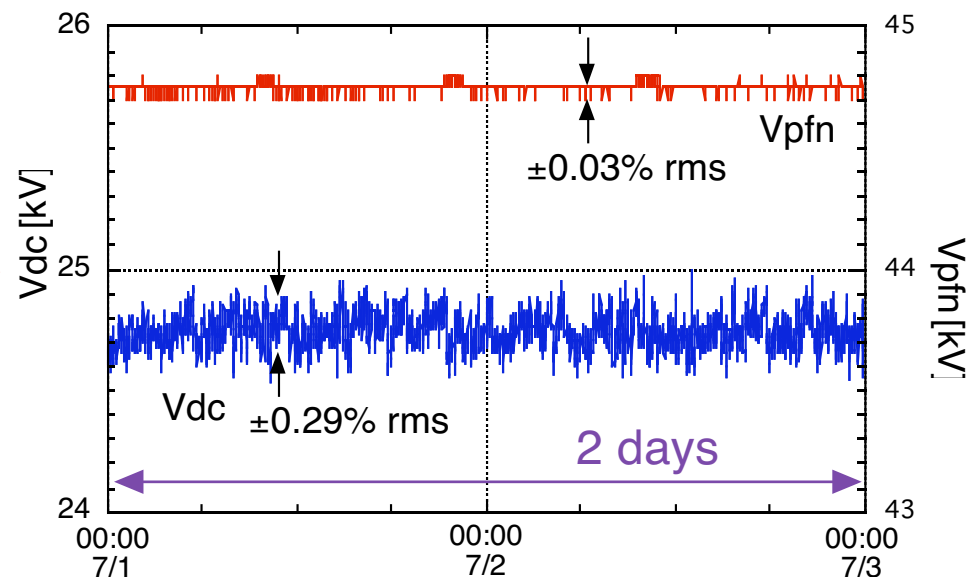
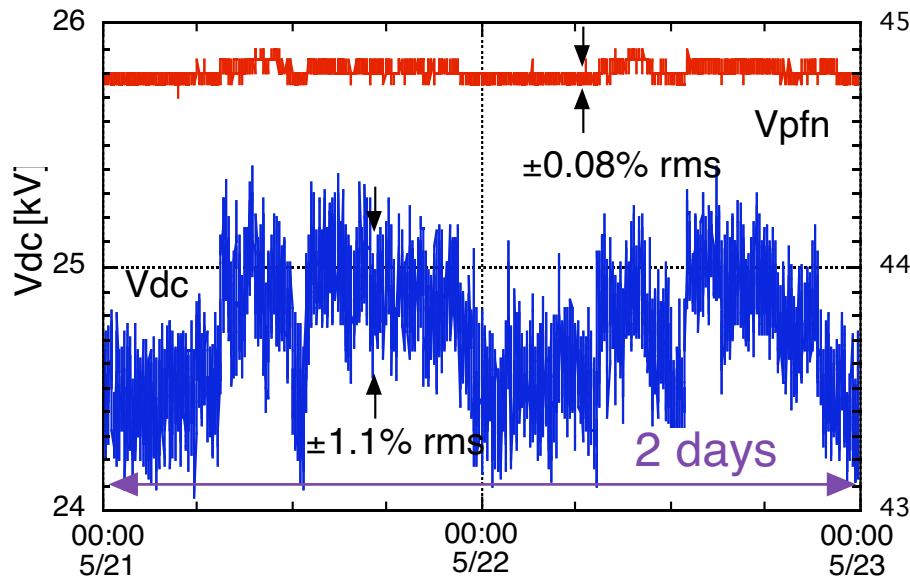
- ▶ Control Induction Voltage Regulator (IVR) to compensate line voltage variation

- ▶ Optimization of de-Q'ing rate
7% → 4%

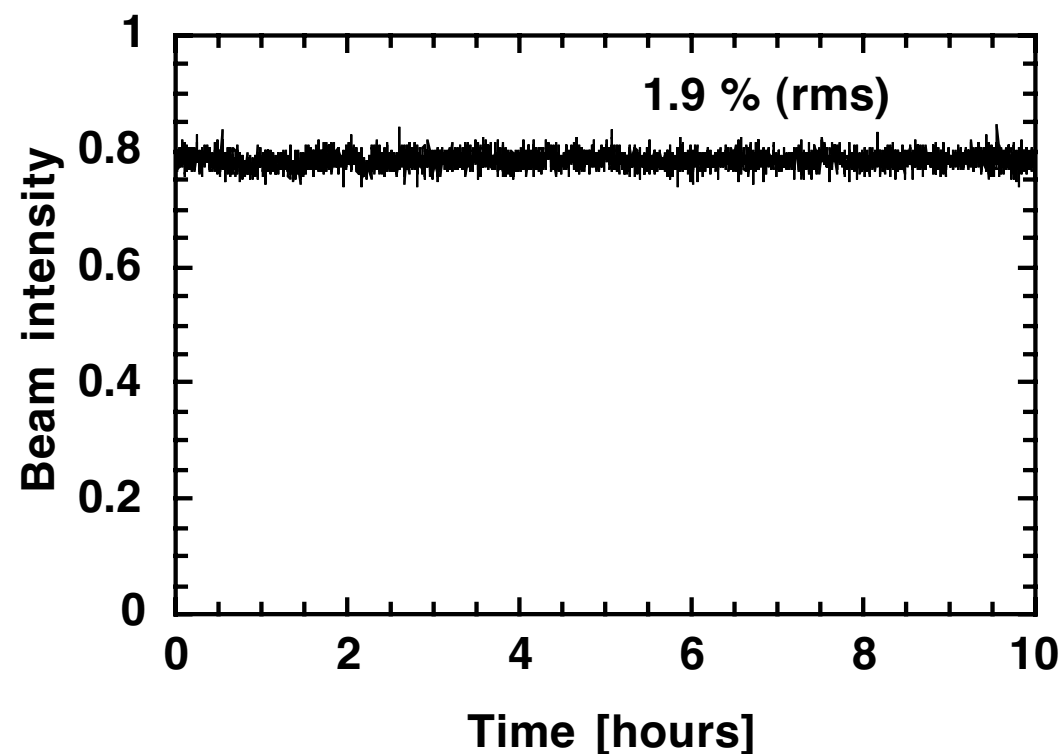
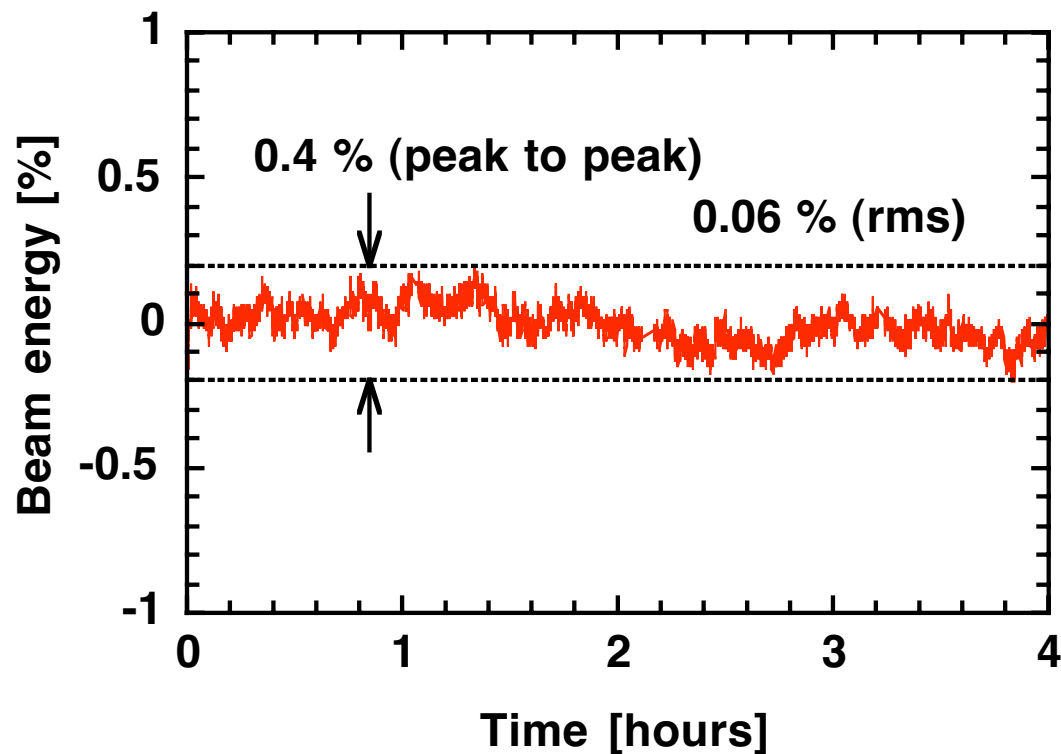
PFN voltage
0.3 % (rms)



0.03 % (rms)



Improved beam stability



Beam energy

> 1 % (10 h)



0.06 % (rms) (4 h)

0.03 % (rms) (10 min)

Beam current

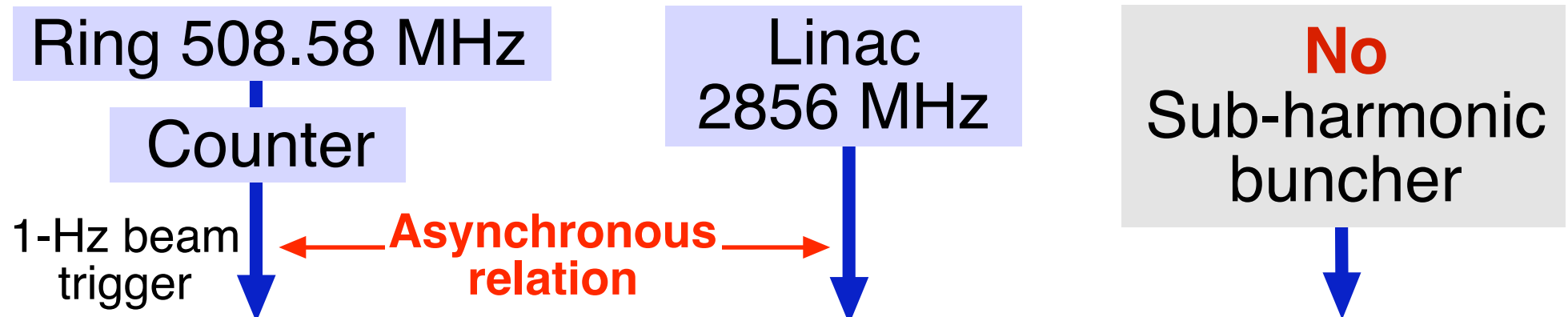
> 20 %



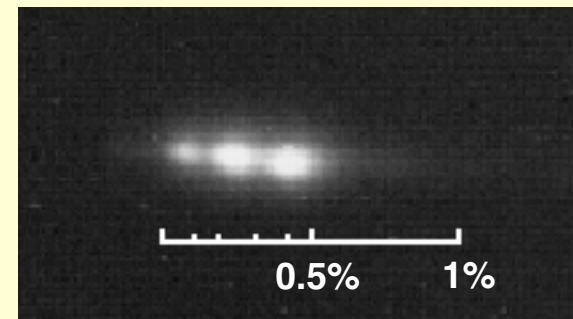
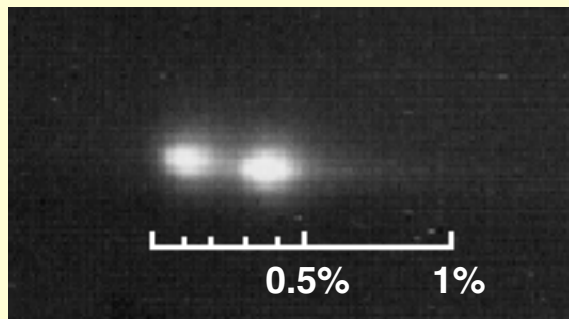
1.9 % (rms)

- 1 Stabilization of RF amplitude & phase
 - ➔ Investigate variation chains
 - Stabilization of their origins or devices
- 2 Reduce **beam loading fluctuation** ← **No SHB!**
 - ➔ Synchronization of linac RF with ring RF
- 3 Compensate accidental energy variation
 - ➔ Introduce Energy Compression System (ECS)
- 4 Reduce residual beam position drift
 - ➔ Introduce feedback control

Asynchronous RF issue before 2001



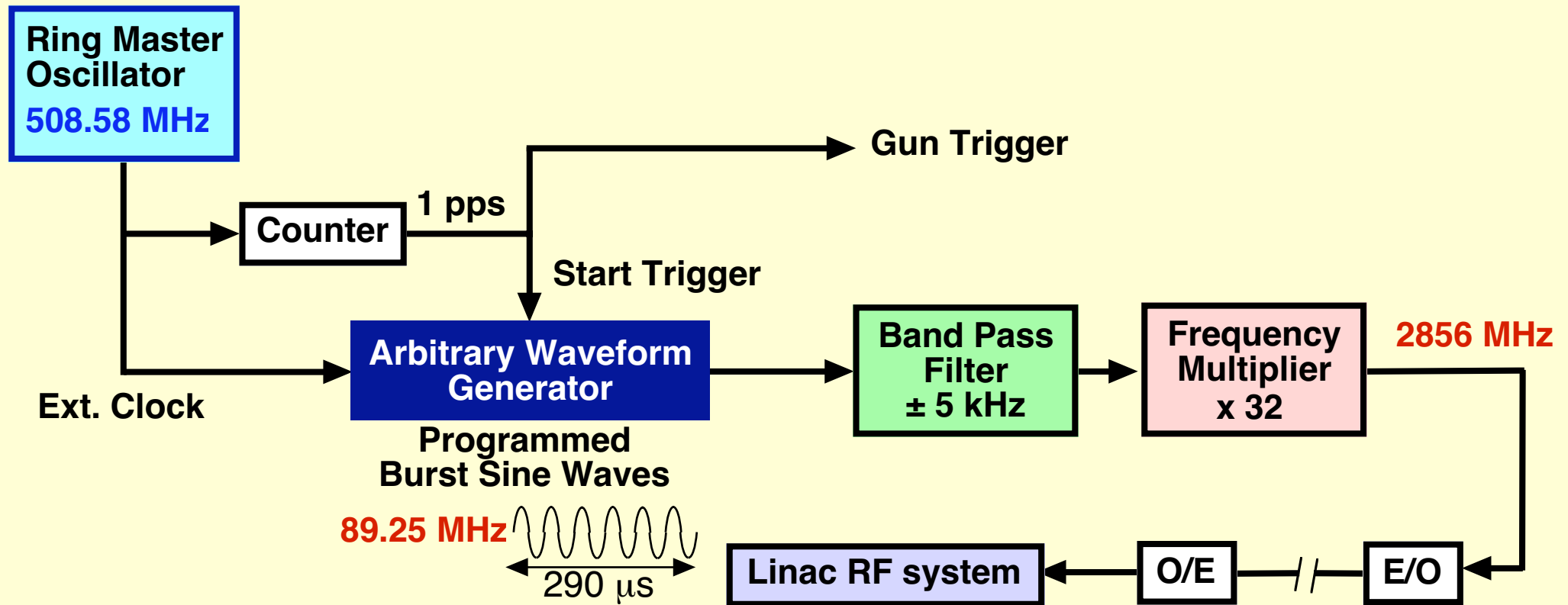
Asynchronous 2856-MHz RF forms two or three bunches along with beam trigger timing referred to the RF phase.



Energy distribution of 1-ns beam (@1.9A)

- ▶ Unstable beam energy at high current
- ▶ Unstable current of single-bunch beam

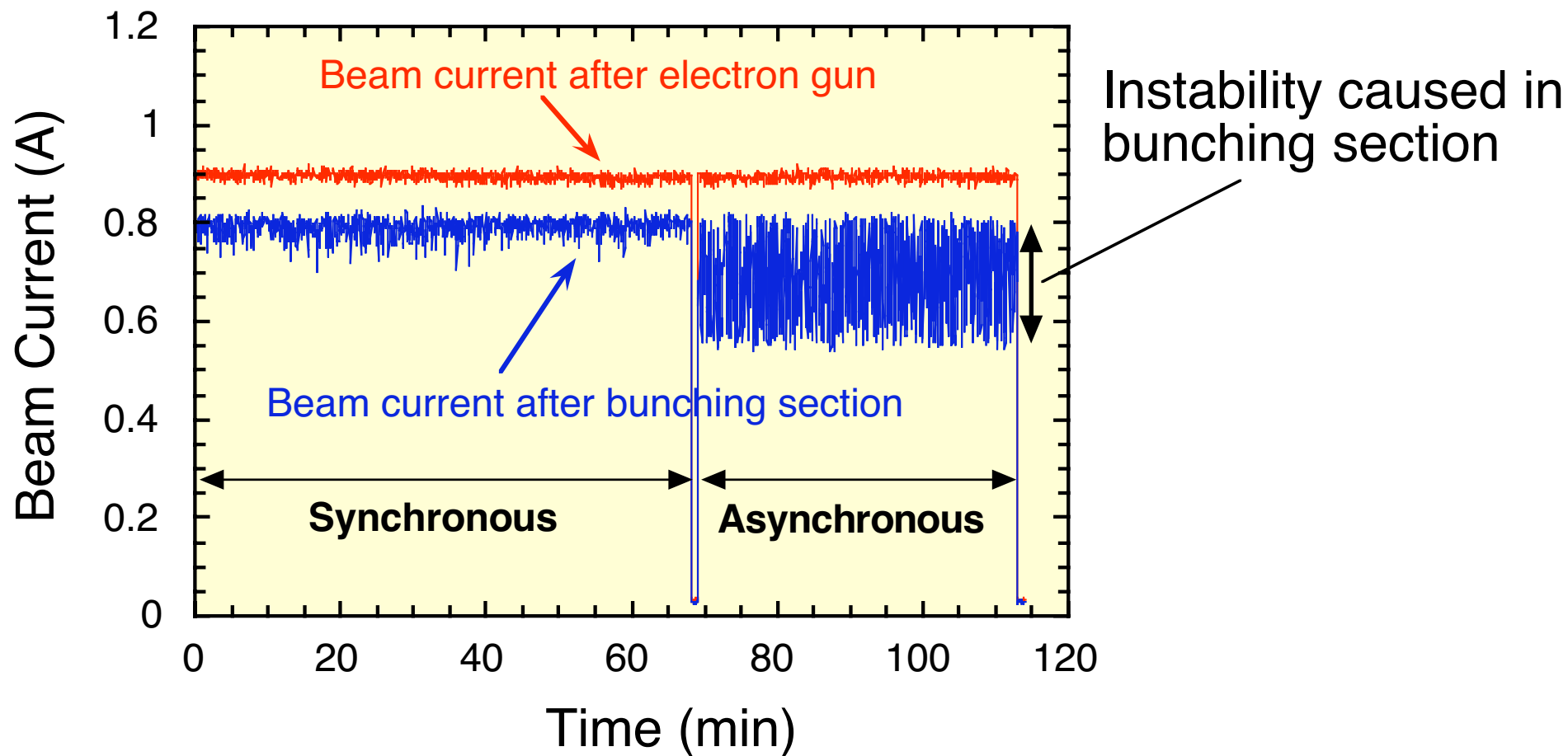
New synchronous oscillator



- ▶ A start signal synchronous to 508.58 MHz starts the AWG to generate a **burst wave** of 89.25 MHz
- ▶ A narrow band pass filter reduces phase noises

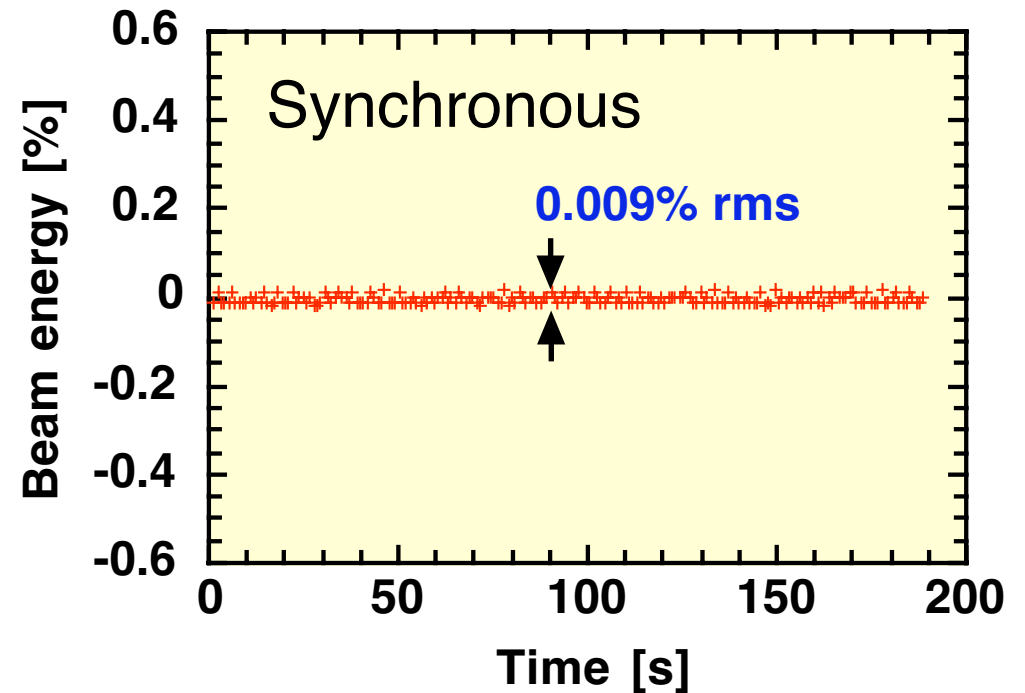
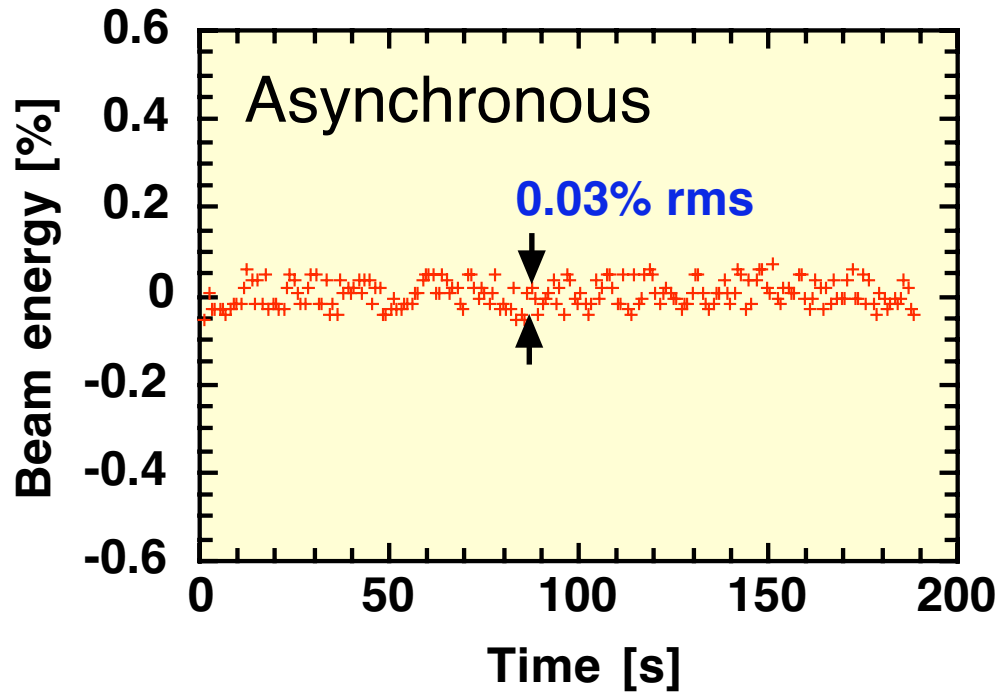
Single-bunch current stability

Beam pulse width : 250 ps



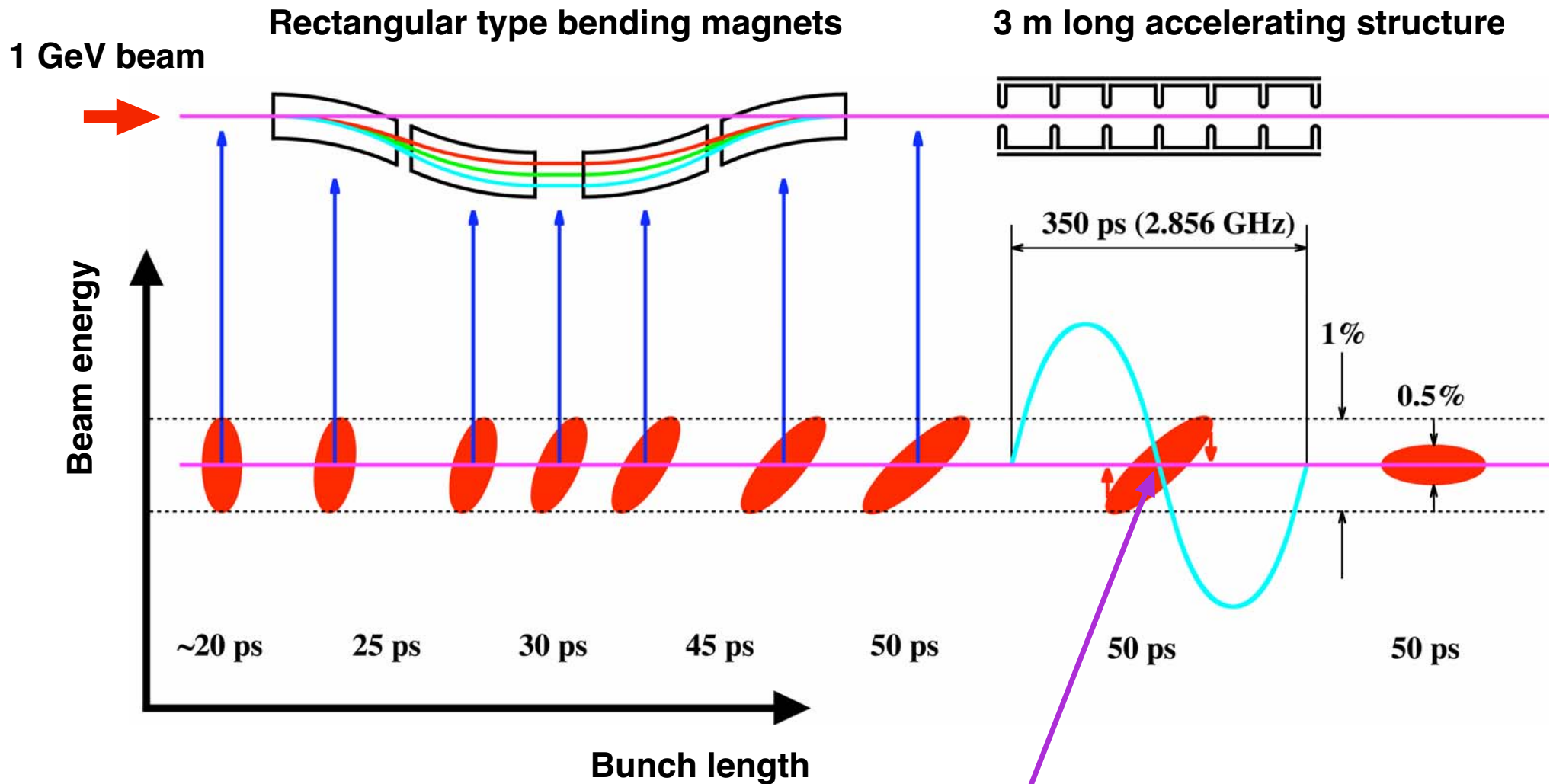
Beam energy stability at high current

1-ns beam energy at 1.4 A



- 1 Stabilization of RF amplitude & phase
 - ➔ Investigate variation chains and fix their origins
- 2 Reduce beam loading fluctuation
 - ➔ Synchronization of linac RF with ring RF
- 3 Compensate accidental energy variation
 - ➔ Introduce conventional Energy Compression System (ECS)
- 4 Reduce residual beam position drift
 - ➔ Introduce feedback control

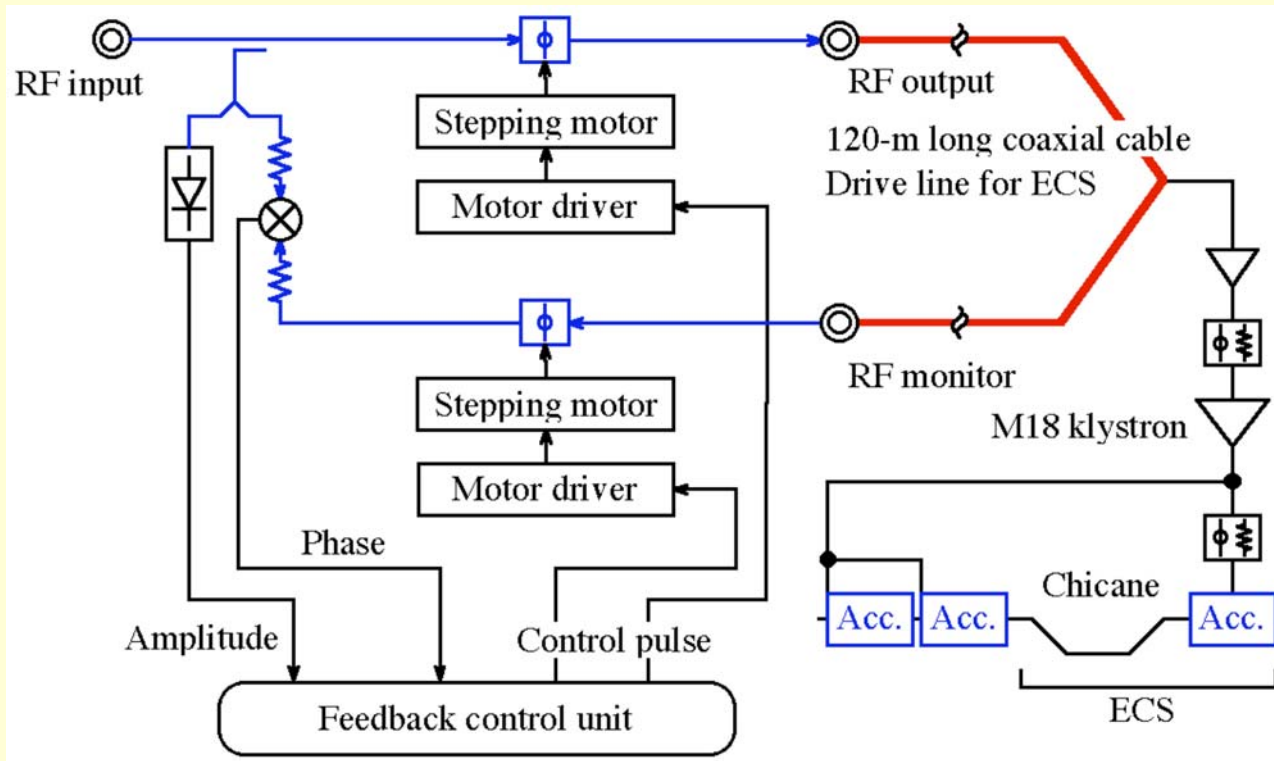
Energy Compression System (ECS)



- ▶ Chicane expands bunch length along with beam energy.
- ▶ ECS compresses beam energy spread and variation.
- ▶ ECS requires RF phase stability

ECS requires RF phase stability

1) PLL circuit for ECS klystron drive system



New synchronous
Oscillator

Phase variation
0.2 deg. rms

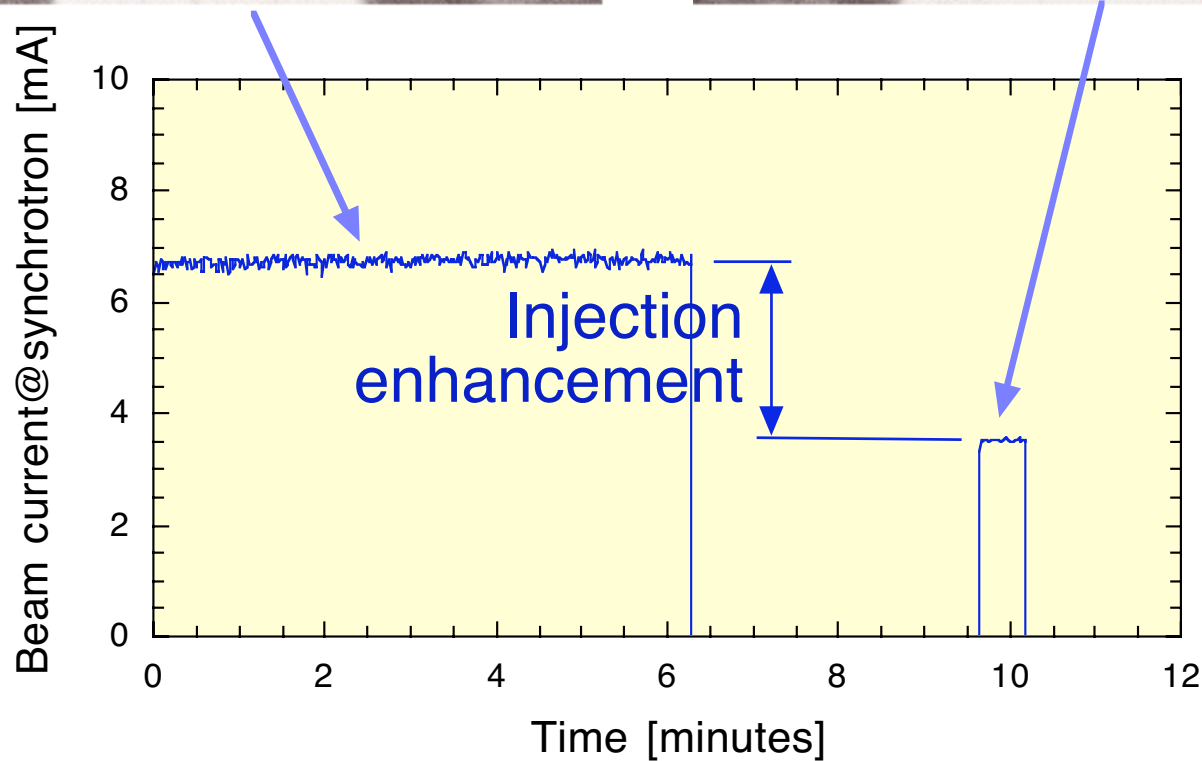
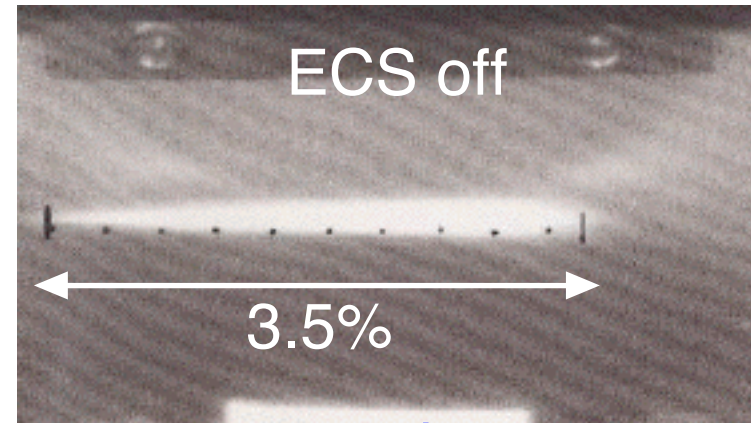
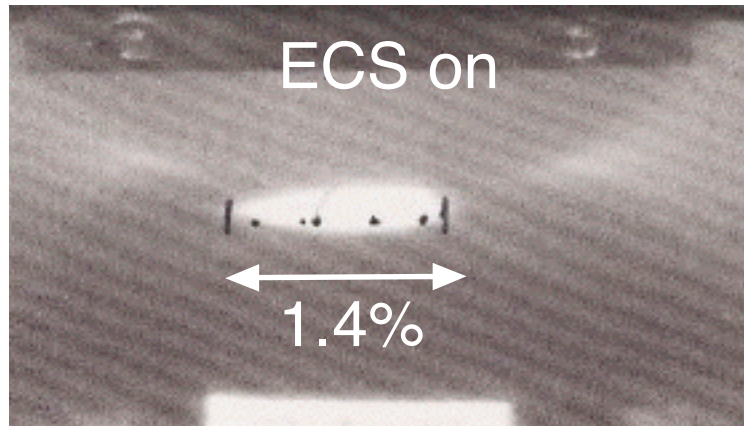
2) Klystron voltage > 350 kV

Phase variation
0.2 deg. rms

ECS Phase instability: 0.3 deg. rms
Energy instability : ~ **0.01%** rms

ECS compressed beam energy spread

40-ns beam at 350 mA



- 1 Stabilization of RF amplitude & phase
 - ➔ Investigate variation chains and fix their origins
- 2 Reduce beam loading fluctuation
 - ➔ Synchronization of linac RF with ring RF
- 3 Compensate accidental energy variation
 - ➔ Introduce conventional Energy Compression System (ECS)
- 4 Reduce residual beam position drift
 - ➔ Introduce feedback control

Problem: beam position drift

Beam position drift at the linac upstream

- Small betatron oscillation
- Beam position drift at the injection points

Solution: beam position feedback control

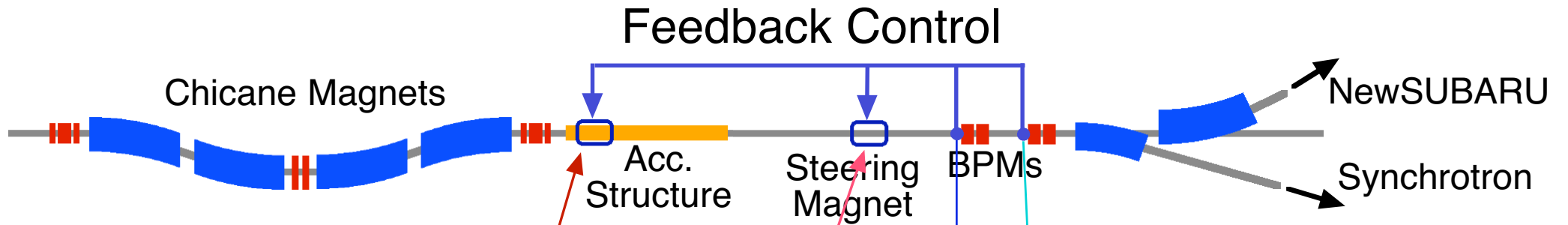
Beam position stabilization at BT lines

- Injector part
- Linac end
- Long BT to the NewSUBARU storage ring

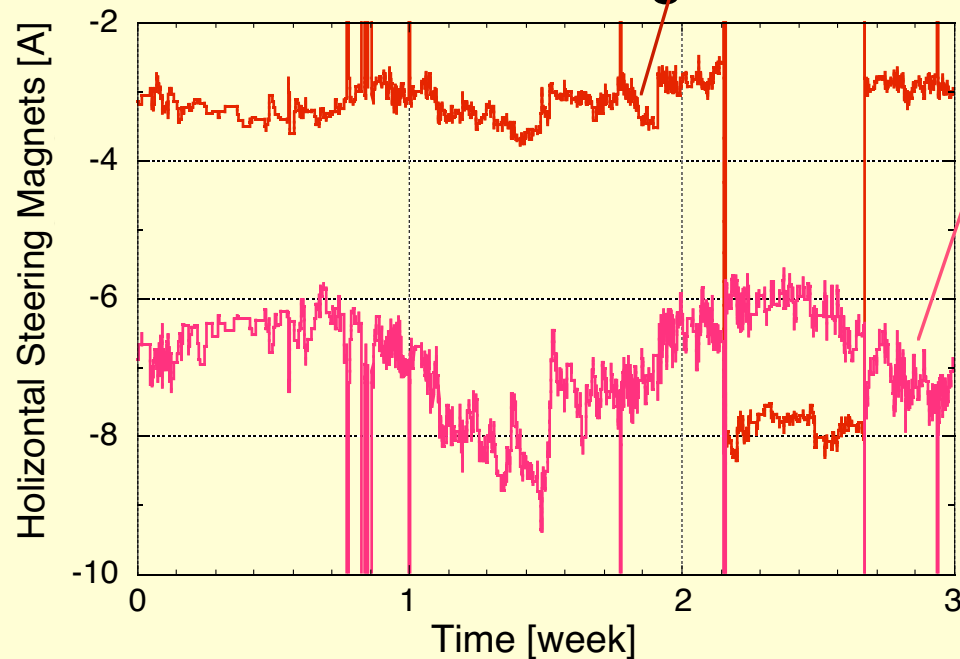
Control steering magnets referring to BPM data

- Position window: $60\mu\text{m}$
- Response time: a few minutes

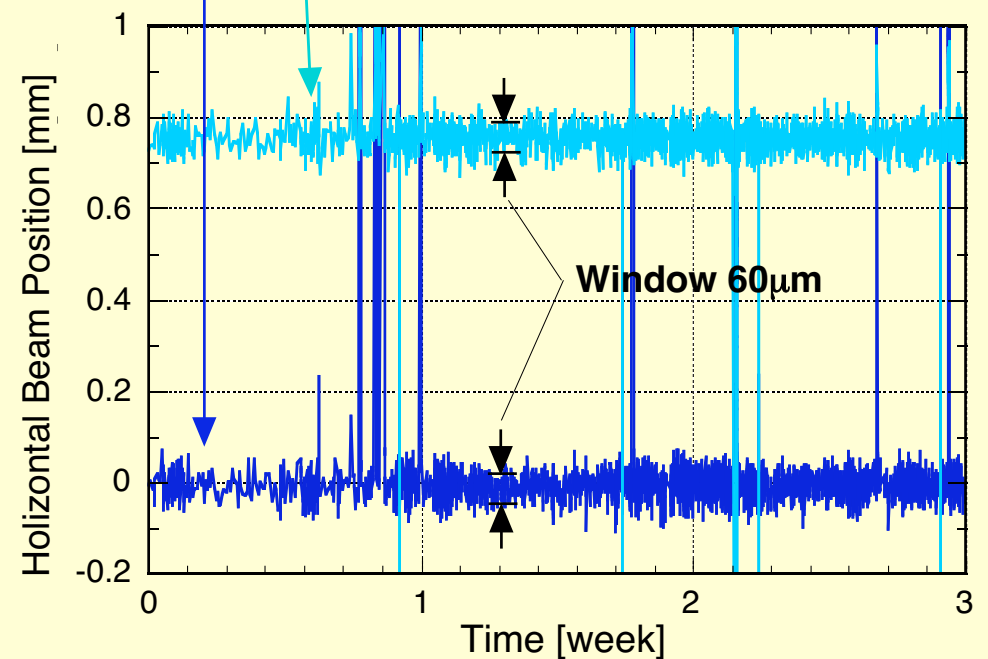
Beam Position Feedback Control



Automatic Steering Control



Stabilized Beam Position



- 1 Stabilization of RF amplitude & phase
 - ➔ Investigate variation chains
 - Stabilization of their origins or devices
 - ➔ **Energy instability: 0.03% rms**
- 2 Reduce beam loading fluctuation
 - ➔ Synchronization of linac RF with ring RF
 - ➔ **Energy instability: < 0.01% rms**
- 3 Compensate uncontrollable energy variation
 - ➔ Introduce Energy Compression System (ECS)
 - ➔ **Long and short term stability**
 - ➔ **High current injection**
- 4 Reduce residual beam position drift
 - ➔ Introduce feedback control
 - ➔ **Position stability: 60 μm**